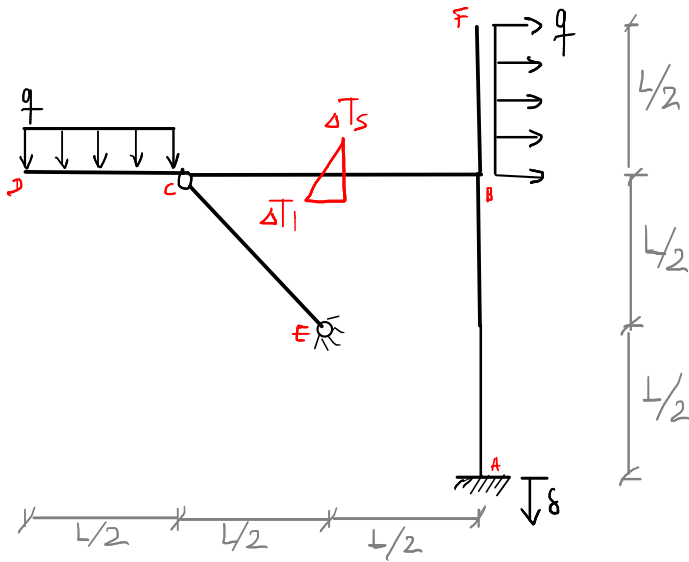


Find the internal actions N, V and M for the presented structure.



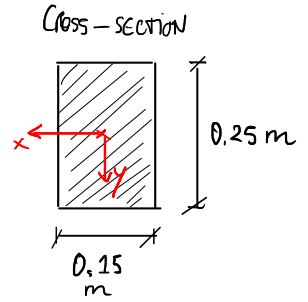
$\Delta T_i = 30^\circ\text{C} ; \Delta T_s = 0^\circ$

$q = 20 \text{ kN/m} , \delta = 1 \text{ cm}$

$L = 4 \text{ m}$

$E = 206 \text{ GPa}$

$\alpha = 1 \times 10^{-5} / ^\circ\text{C}$



1 Degree of static indeterminacy: *number of dof*

$DSI = ED + ID = (+5 - 3) + (-1) = +1 //$ hyperstatic 1 time
number of reactions *hinge*

OR
 $DOCs = +3_{(A)} + 2_{(C)} + 2_{(E)} = 7$

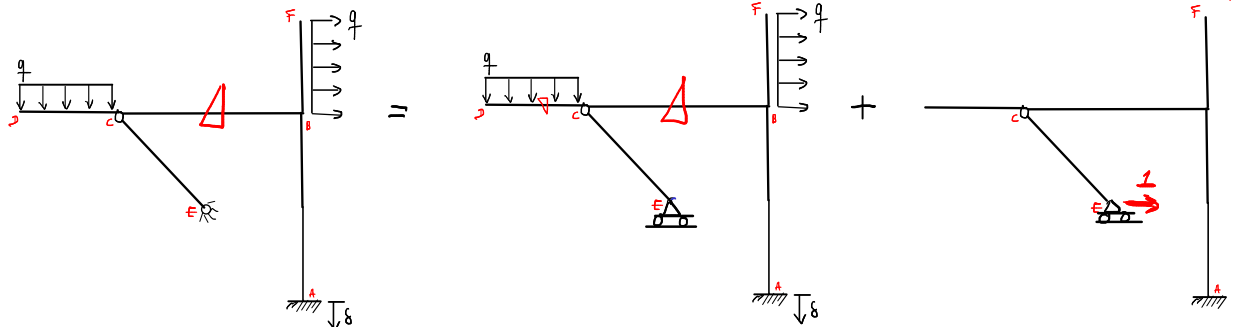
$DOFs = 2 \times 3 = 6$
number of bars *number of dofs*

$DOCs > DOFs \Rightarrow 7 - 6 = +1 //$ hyperstatic 1 time

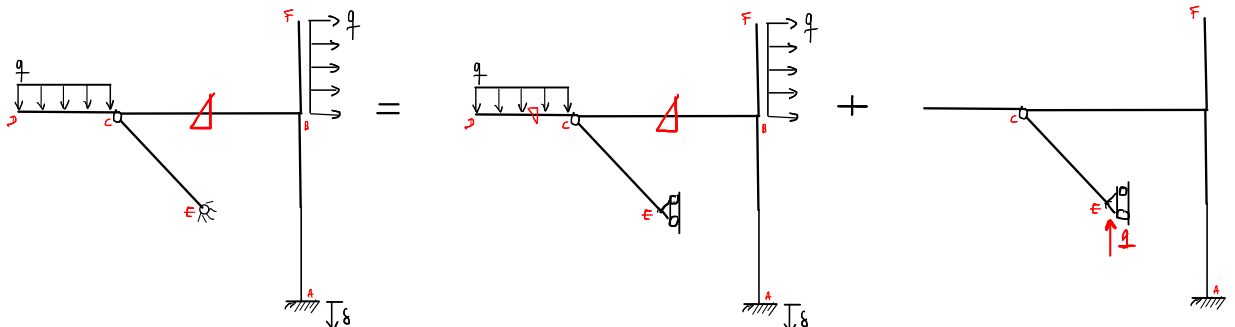
2 Definition of the BASE SYSTEM and VIRTUAL SYSTEM (superposition of effects)

REAL (HYPERSTATIC) = BASE (ISOSTATIC) + VIRTUAL (ISOSTATIC)

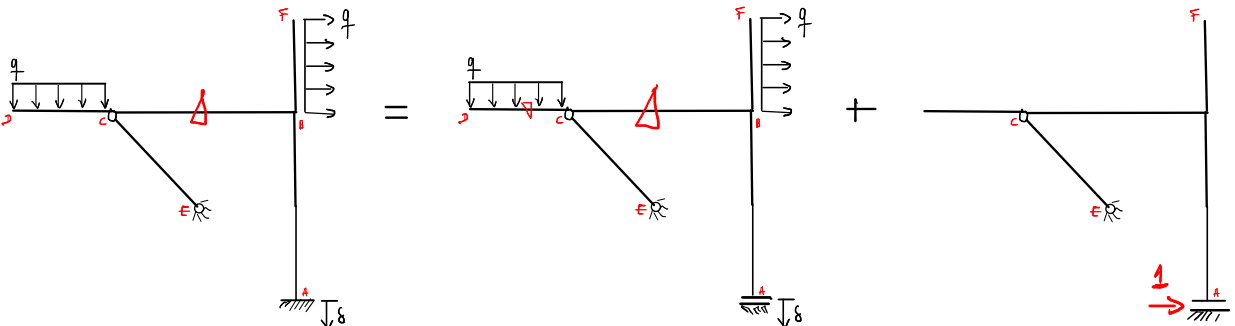
Option 1



Option 2

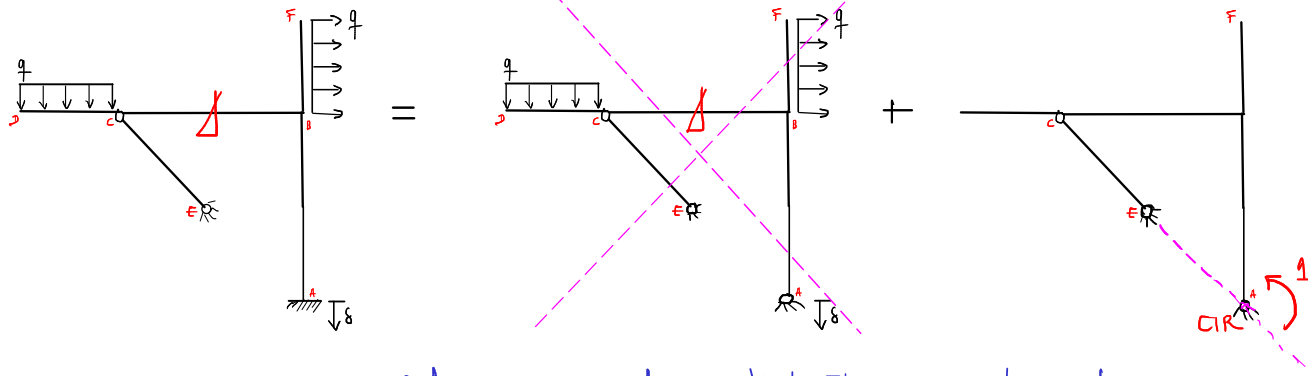


Option 3





Option 4



Option 4 is not possible! It is a mechanism!

Let us select option 3

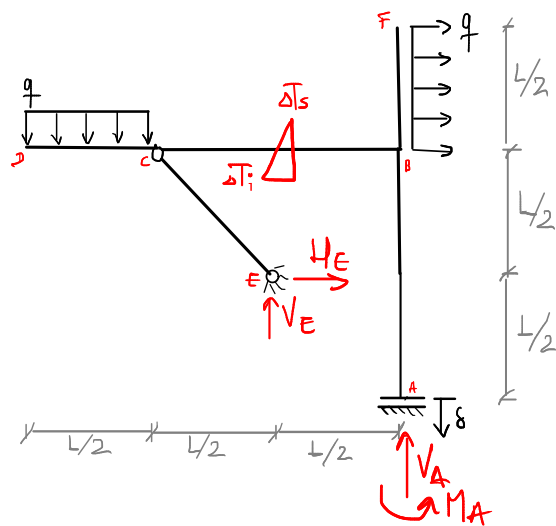
3 PRINCIPAL OF VIRTUAL WORK \Rightarrow COMPATIBILITY CONDITION

- I. The hyperstatic unknown is a horizontal Reaction in A;
 II. this means that the compatibility equation is written in terms of displacements;

$$\overset{0}{u}_{Ax} + \sum \overset{1}{u}_{Ax} = 0$$

BASE ROTATION
VIRTUAL ROTATION
REAL ROTATION

4 STUDY OF THE BASE SYSTEM, 0

GLOBAL EQUILIBRIUM (Reactions) (4 unknowns \Rightarrow 4 EQUATIONS)

$$\begin{aligned} \rightarrow \sum F_x = 0 & \quad \left\{ \begin{aligned} H_C + qL/2 = 0 & \Rightarrow H_C = -qL/2 \text{ (W)} \\ V_A + V_C - qL/2 = 0 \\ M_A - qL/2 \cdot (L + L/4) + qL/2 \cdot (L + L/4) - H_C \cdot L - V_C \cdot L/2 = 0 \\ H_C \cdot L/2 + V_C \cdot L/2 = 0 \end{aligned} \right. \\ \uparrow \sum F_y = 0 & \\ \curvearrowright \sum M_A = 0 & \\ \curvearrowright \sum M_C^{\text{right}} = 0 & \end{aligned}$$

$$| H_C = -qL/2 \Rightarrow \text{correct } H_C = qL/2 \text{ (W)} \leftarrow$$

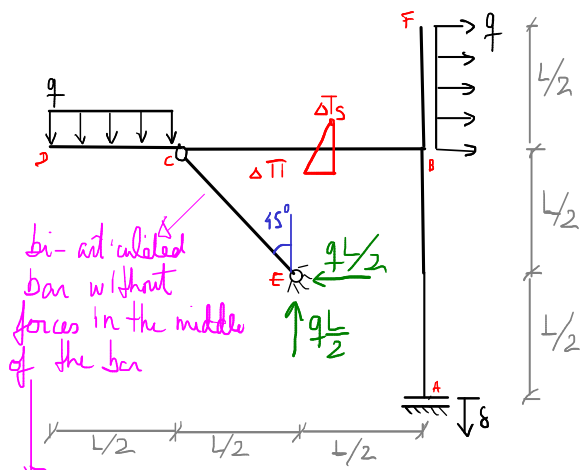
$$V_A + qL/2 - qL/2 = 0 \Rightarrow V_A = 0 \quad \oplus \quad V_A = 0$$

$$M_A + qL/2 \cdot L/2 - qL/2 \cdot L/2 = 0 \Rightarrow M_A = 0 \quad \oplus \quad M_A = 0$$

$$-qL/2 \cdot L/2 + V_C \cdot L/2 = 0 \Rightarrow V_C = qL/2 \text{ (W)} \quad V_C = qL/2 \text{ (W)} \uparrow$$

4.1 Internal Actions

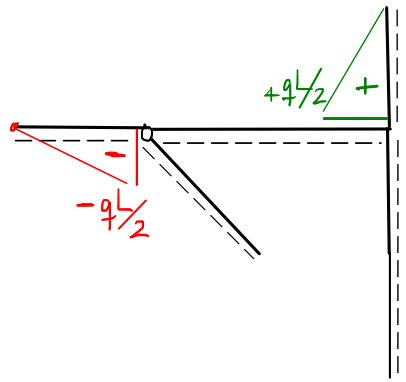
left ($\leftarrow \uparrow \oplus \downarrow \rightarrow$) right



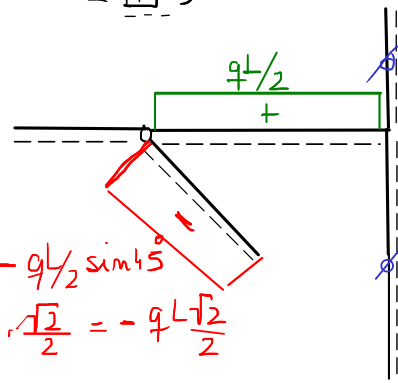
bi-articulated bar without forces in the middle of the bar

only axial force (like TRUSS BAR)

$V^0 (kN)$
↑ ⊕ ↓

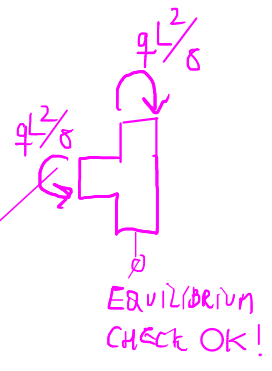
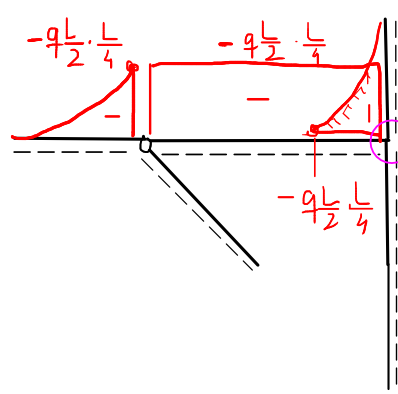


$\int V^0 (kN)$
← ⊕ →

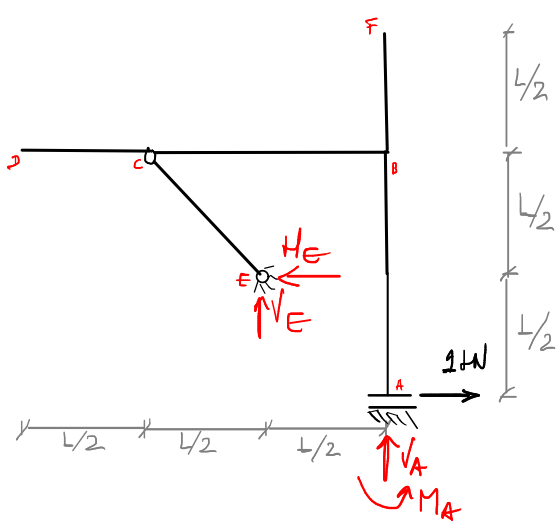


$= -\frac{qL}{2} \cdot \cos 45 - \frac{qL}{2} \sin 45$
 $= -2 \frac{qL}{2} \cdot \frac{\sqrt{2}}{2} = -qL \frac{\sqrt{2}}{2}$

$M^0 (kNm)$
↑ ⊕ ↓



5 STUDY OF THE VIRTUAL SYSTEM



$\rightarrow \sum F_x = 0 \Leftrightarrow -H_e + 1 = 0 \Leftrightarrow H_e = 1 \text{ kN} (\leftarrow)$ (1)

$\uparrow \sum F_y = 0 \Leftrightarrow V_A + V_e = 0 \Leftrightarrow V_A = -V_e \Leftrightarrow V_A = -1 \text{ kN}$ (3)

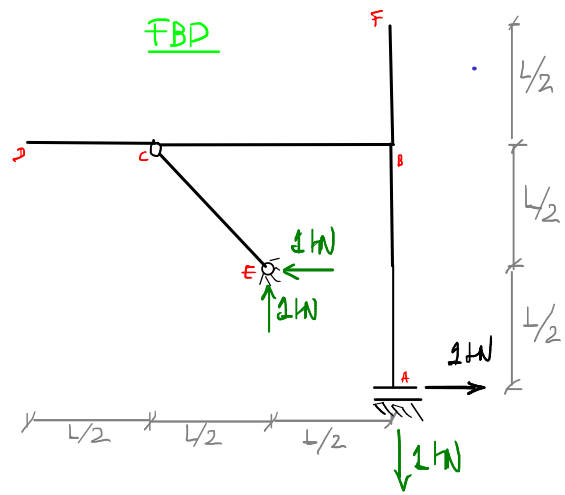
correct the sense

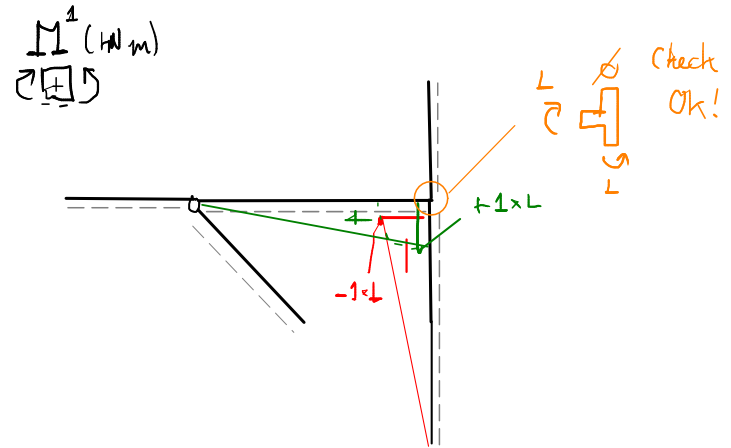
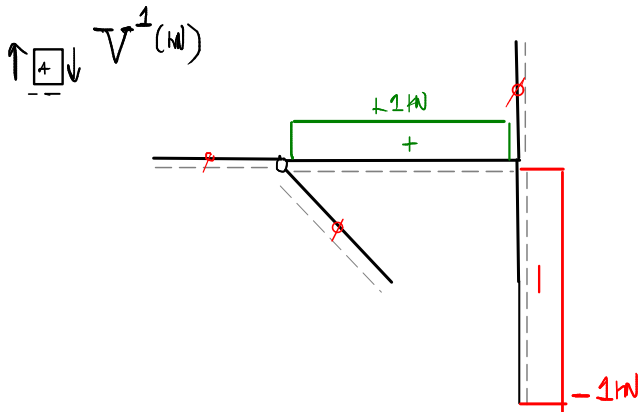
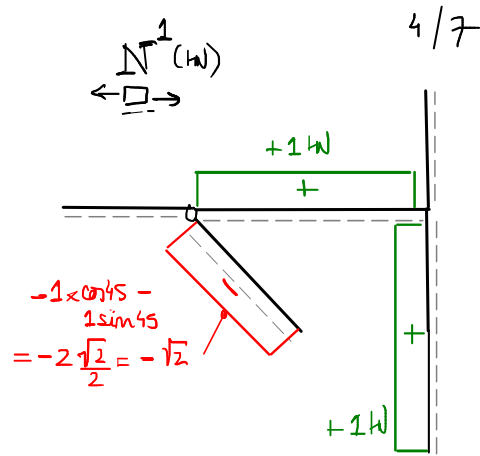
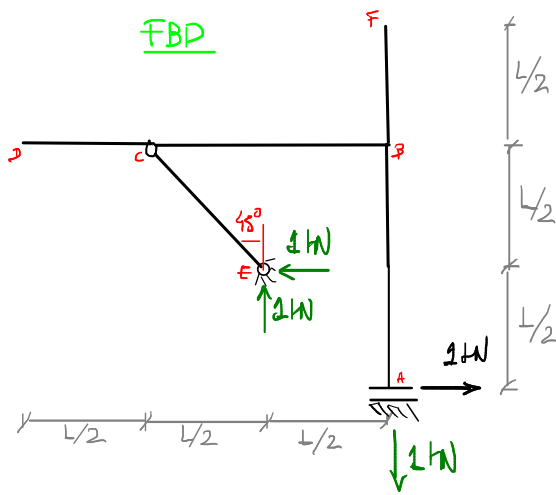
$\curvearrowright \sum M_A = 0 \Leftrightarrow M_A + H_e \cdot \frac{L}{2} - V_e \cdot \frac{L}{2} = 0 \Leftrightarrow M_A = 0$ (4)

$\curvearrowright \sum M_C^{\text{right}} = 0 \Leftrightarrow -H_e \cdot \frac{L}{2} + V_e \cdot \frac{L}{2} = 0 \Leftrightarrow V_e = H_e \Leftrightarrow V_e = 1 \text{ kN} (\uparrow)$ (2)

Correct the sense of V_A : $V_A = 1 \text{ kN} (\downarrow)$

5.1 Internal Actions





6 SOLVING THE COMPATIBILITY CONDITION

$$u_{Ax}^0 + \sum u_{Ax}^1 = 0$$

BASE ROTATION + VIRTUAL ROTATION = REAL ROTATION

BASE SYSTEM 0 × VIRTUAL SYSTEM 1

6.1 SOLVING u_{Ax}^0

$$\delta = \int \epsilon \, ds = \int \frac{\sigma}{E} \, ds = \int \frac{N}{EA} \, ds + \int \frac{V}{GA} \, ds + \int \frac{M}{EI} \, ds + \int \alpha \Delta T \, ds + \int \frac{M}{h} \, ds$$

Wext = Wint ⇔

$$\ominus 1 \times u_{Ax}^0 + \sum R_i \delta_i = \int \frac{N^1 N^0}{EA} \, dx + \int \frac{V_1 V_0}{GA} \, dx + \int \frac{M^1 M^0}{EI} \, dx + \int N^1 \alpha \Delta T \, dx + \int \frac{M^1 \alpha \Delta T d}{h} \, dx$$

① settlements. Only in A

② ignore

③ temperature effects

① Wext = $u_{Ax}^0 + (1 \times \delta)$ because reaction in A in the virtual system has the same sense of the settlement

② $\int \frac{N^1 N^0}{EA} \, dx = \frac{1}{EA} \left(\int_{BC} \left(\frac{L}{2} \right) \left(-\frac{L}{\sqrt{2}} \right) dx + \int_{AB} (1) (1) dx \right)$

Area of triangle for diagonal member: $\frac{1}{2} \times \frac{L}{2} \times \frac{L}{2} = \frac{L^2}{8}$

$$= \frac{1}{EA} \left(-\frac{qL}{2} \cdot \frac{L}{\sqrt{2}} \cdot \left(-\frac{L}{\sqrt{2}} \right) \right) + \frac{1}{EA} \left(qL \cdot L \cdot (+1) \right) = \frac{1}{EA} \left(+\frac{qL^2}{2} \sqrt{2} + qL^2 \right)$$

③ $\int_L \frac{M^1 M^0}{EI} dx = \frac{1}{EI} \left(\text{Bar CB} \times \text{Area} \times \frac{L}{2} \right) = \frac{1}{EI} \left(-\frac{qL^2}{8} \times L \times \frac{L}{2} \right) = -\frac{qL^4}{16EI}$

④ temperature effects

$\int_L N^1 \alpha \Delta T_0 dx = \left(\text{Bar CB} \times \text{Area} \times \frac{\Delta T_s + \Delta T_i}{2} \right) = 1 \times L \times \alpha \times \frac{\Delta T_s + \Delta T_i}{2}$

⑤ $\int_L \frac{M^1 \alpha \Delta T_d}{h} dx = \left(\text{Bar CB} \times \frac{L^2}{2} \times \alpha \times \frac{\Delta T_i - \Delta T_s}{h} \right) = \frac{L^2}{2} \cdot \alpha \cdot \frac{\Delta T_i - \Delta T_s}{h}$

Replacing,

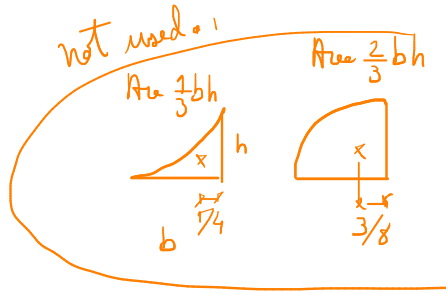
$u_{Ax}^0 + (1 \times \delta) = \frac{N}{EA} \left(+\frac{qL^2}{2} \sqrt{2} + \frac{qL^2}{2} \right) - \frac{M}{EI} - \frac{\Delta T_u}{2} + \frac{\Delta T_D}{2} + \frac{\Delta T_D}{2} \cdot \alpha \cdot \frac{\Delta T_i - \Delta T_s}{h}$

$u_{Ax}^0 = \frac{N}{EA} \left(+\frac{qL^2}{2} \sqrt{2} + \frac{qL^2}{2} \right) - \frac{M}{EI} + \frac{\Delta T_u}{2} + \frac{\Delta T_D}{2} - \frac{\Delta T_D}{2} \cdot \alpha \cdot \frac{\Delta T_i - \Delta T_s}{h} - (1 \times \delta)$ *settlement*

6.2 - SOLVING u_{Ax}^1

West = Wint (two times the virtual system)

$1 \times u_{Ax}^1 = \int_L \frac{N^1 N^1}{EA} dx + \int_L \frac{M^1 M^1}{EI} dx$



① $\int_L \frac{N^1 N^1}{EA} dx = \frac{1}{EA} \left(\text{Bar AB} \times \text{Area} \times (+1) \times (+1) + \text{Bar BC} \times \text{Area} \times (+1) \times (+1) + \text{Bar CE} \times \text{Area} \times (-\sqrt{2}) \times (-\sqrt{2}) \right)$

$= \frac{1}{EA} \left(L + L + \left(-\sqrt{2} \times \frac{L}{\sqrt{2}} \right) \times \left(-\sqrt{2} \right) \right) = \frac{1}{EA} \left(2L + \sqrt{2}L \right)$

② $\int_L \frac{M^1 M^1}{EI} dx = \frac{1}{EI} \left(\text{Bar AB} \times \text{Area} \times \left(-L \right) \times \left(\frac{2}{3}(-L) \right) + \text{Bar BC} \times \text{Area} \times \left(\frac{L}{2} \right) \times \left(\frac{2}{3}L \right) \right) = \frac{2}{EI} \left(\frac{L^2}{2} \cdot \frac{2}{3}L \right) = \frac{2}{3} \frac{L^3}{EI}$

Replacing,

$u_{Ax}^1 = \frac{1}{EA} \left(2L + \sqrt{2}L \right) + \frac{1}{EI} \left(\frac{2}{3} L^3 \right)$

6.3 Hyperstatic Unknown X

$$u_{Ax}^0 + X u_{Ax}^1 = 0$$

$$\left[\frac{1}{EA} \left(+\frac{qL^2\sqrt{2}}{2} + \frac{qL^2}{2} \right) - \frac{qL^4}{16EI} + 1 \times L \times \alpha \times \frac{\Delta T_s + \Delta T_i}{2} + \frac{L^2}{2} \cdot \alpha \cdot \frac{\Delta T_i - \Delta T_s}{h} - (1 \times \delta) \right] + \dots$$

$$\dots X \cdot \left[\frac{1}{EA} (2L + \sqrt{2}L) + \frac{1}{EI} \left(\frac{2}{3} L^3 \right) \right] = 0$$

knowing that $\delta = 1 \times 10^{-2} \text{ m}$, $L = 4 \text{ m}$, $E = 206 \times 10^6 \text{ kPa}$, $q = 20 \text{ kN/m}$, $T_i = 30^\circ \text{C}$, $T_s = 0^\circ \text{C}$

And calculating: $A = 0.15 \times 0.25 = 0.0375 \text{ m}^2$; $I_{xx} = \frac{bh^3}{12} = \frac{0.15 \times 0.25^3}{12} = 19.53125 \times 10^{-5} \text{ m}^4$

Replacing,

$$X = 7.25 \text{ kN}$$

7 INTERVAL ACTIONS FOR THE HYPERSTRUCTURE STRUCTURE

$$N^R = N^0 + N^1 \cdot X$$

$$V^R = V^0 + V^1 \cdot X$$

$$M^R = M^0 + M^1 \cdot X$$

\Rightarrow Making use of the compatibility equation

